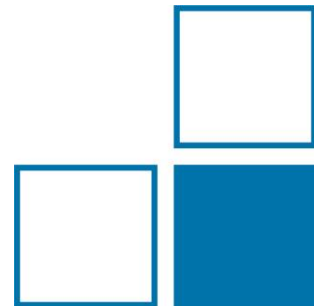


Generative models as prior in Bayesian inverse problems

M. Marschall, G. Wübbeler, F. Schmäling and C. Elster



Motivation: inverse problem

$$y = f(x)$$

Given **observation** y , find **unknown** x .

Example: Image reconstruction

(inpainting, deblurring, denoising,
(non-) parametric regression, ...)



Example solution: **Least-squares** approach

$$\min_x ||y - f(x)||^2 + \mathcal{R}(x)$$

Q: **How to choose the regularizer $\mathcal{R}(x)$?**

Motivation: Bayesian inverse problem

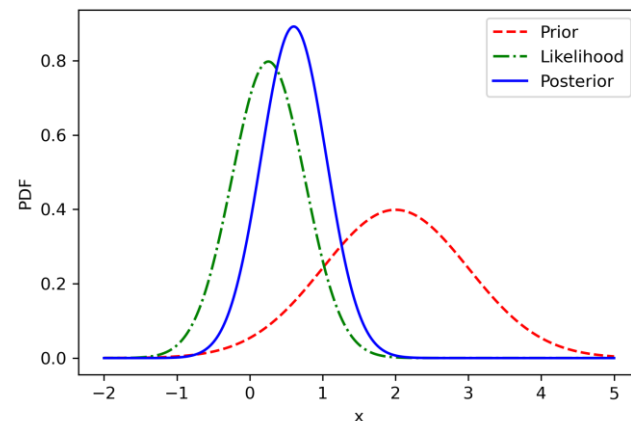
$$y|x, \sigma^2 \sim N(f(x), \sigma^2 I)$$
$$x \sim \pi(x)$$

Given **observation** y , variance σ^2 and **prior** $\pi(x)$, find posterior of **unknown** x .

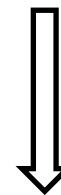
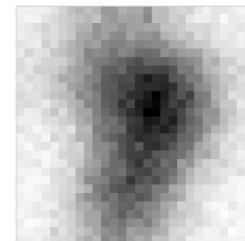
Bayes' Theorem

$$\pi(x | y) \propto L(y | x) \pi(x)$$

Q: **How to choose the prior $\pi(x)$?**

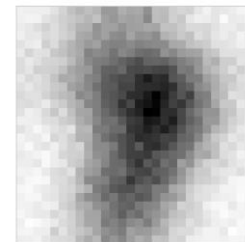
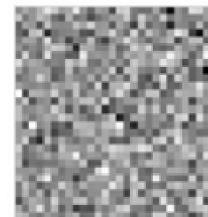
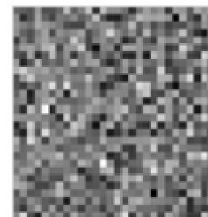
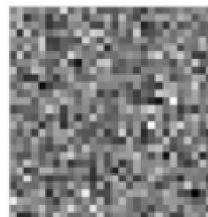
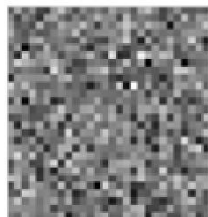
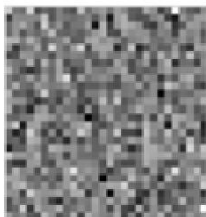


Choosing the prior - visualized



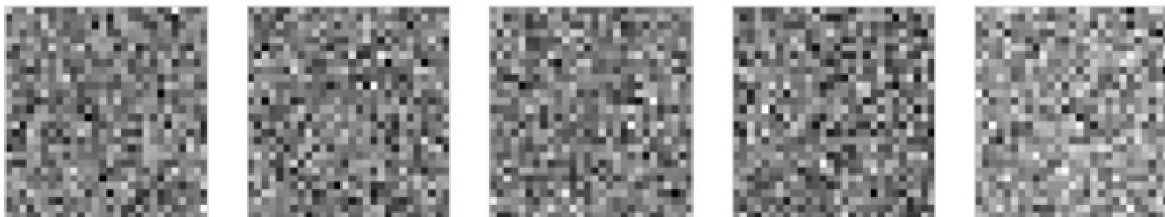
Choosing the prior - visualized

Homoscedastic
Gaussian

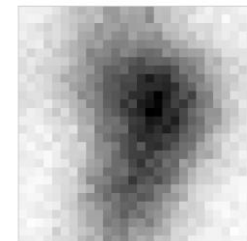
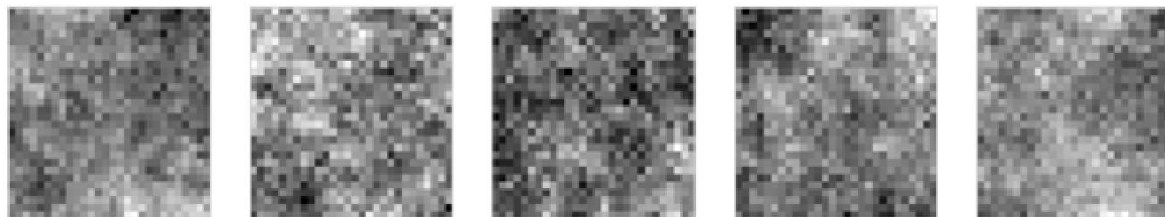


Choosing the prior - visualized

Homoscedastic
Gaussian

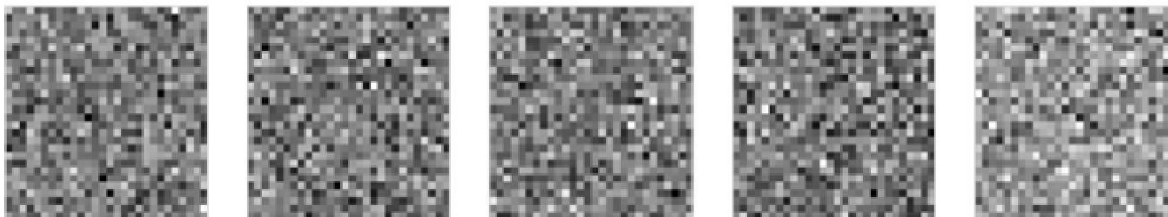


Gaussian Markov
random field

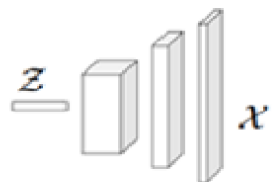
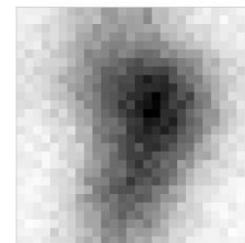
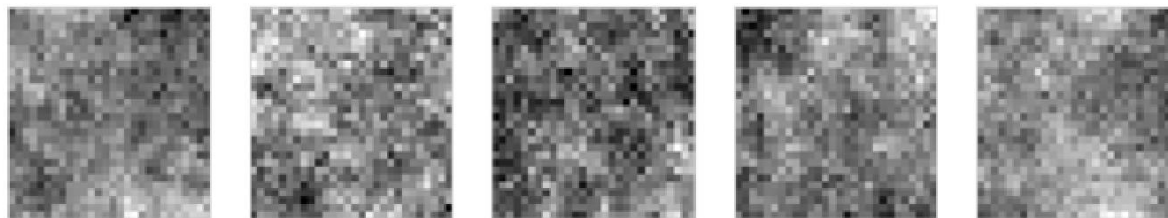


Choosing the prior - visualized

Homoscedastic
Gaussian



Gaussian Markov
random field

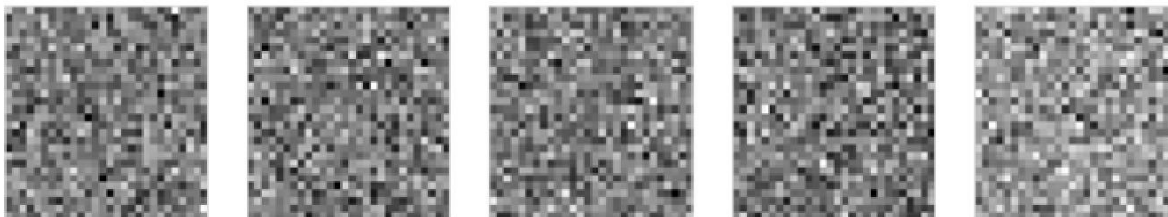


Generative model

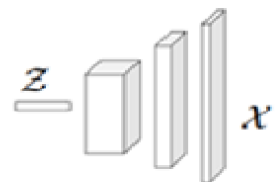
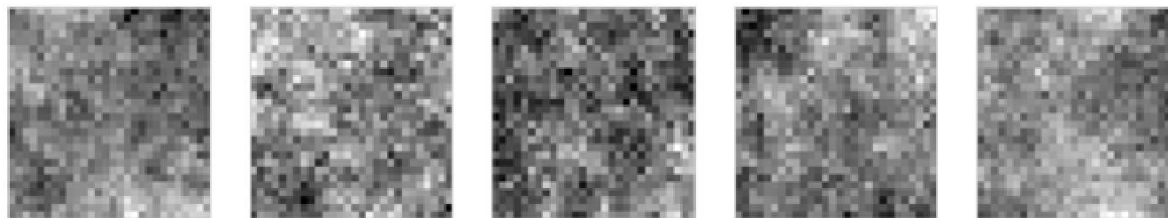


Choosing the prior - visualized

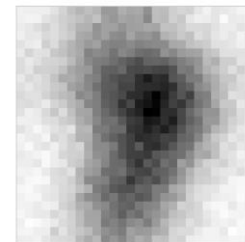
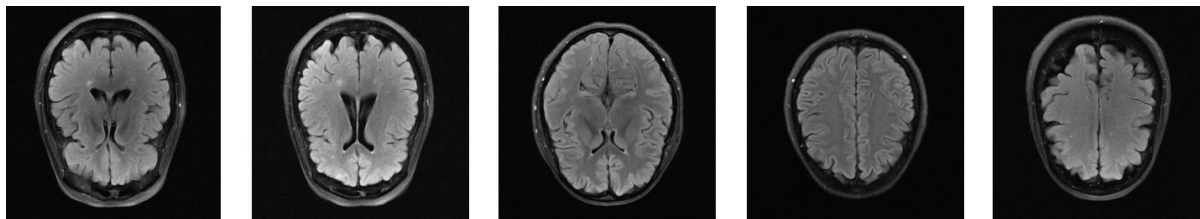
Homoscedastic
Gaussian



Gaussian Markov
random field

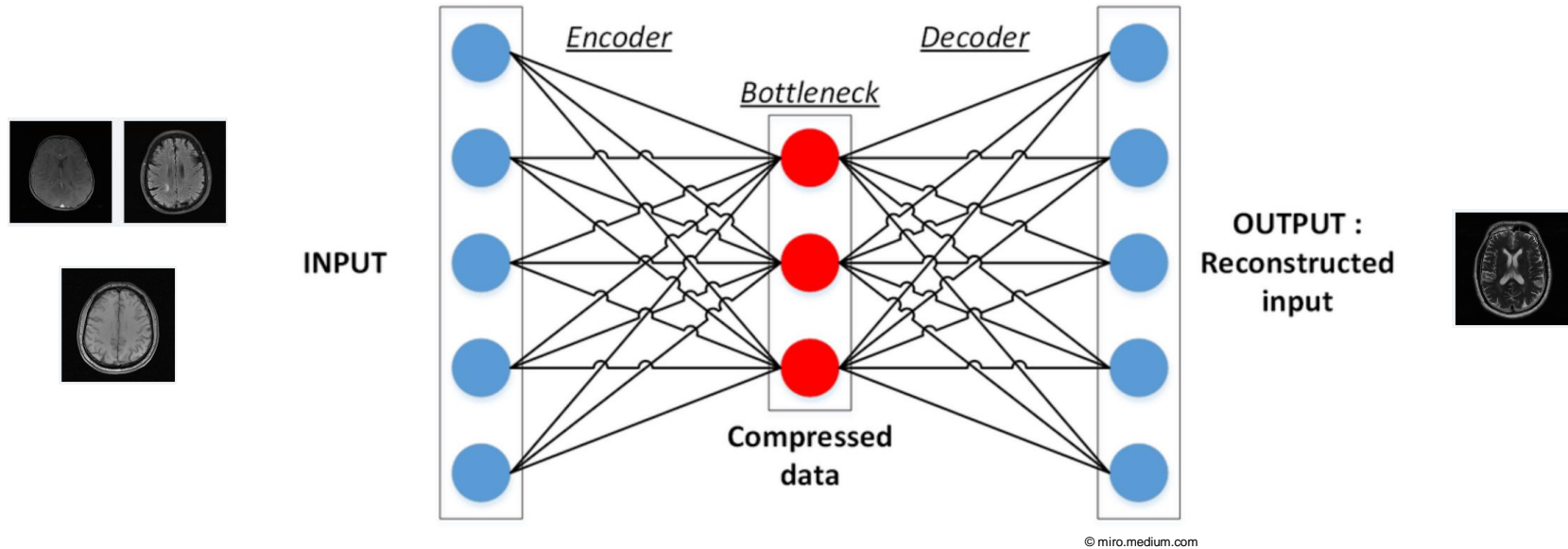


Generative model



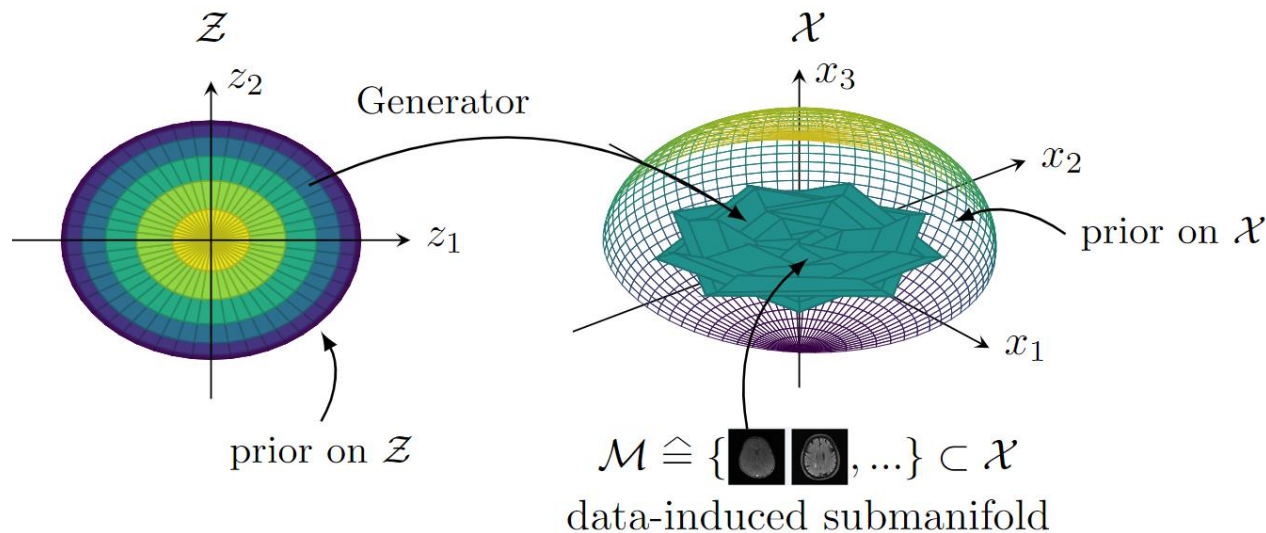
Generative models in machine learning

From latent space to variable space: AE / VAE / GAN / ... / KL / PCE / ... / PCA / ...



$$\text{Variational autoencoder: } z \mid x \sim N\left(e_{\theta_1}(x), \Sigma_{\theta_2}(x)\right), \quad x \mid z \sim N\left(g_{\theta_3}(z), \Gamma_{\theta_4}(z)\right)$$

Latent space vs. Variable space



Inference in latent space

$$y|z \sim N(Ag(z), \sigma^2 I)$$

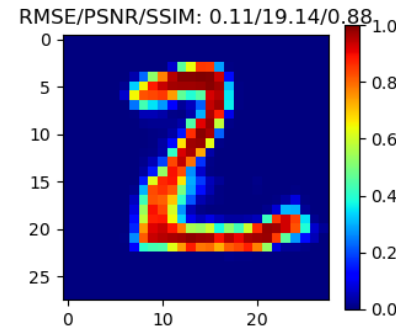
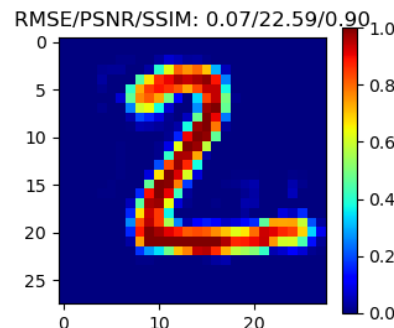
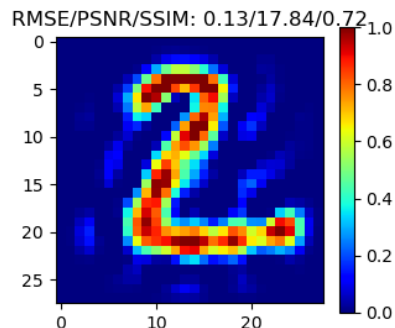
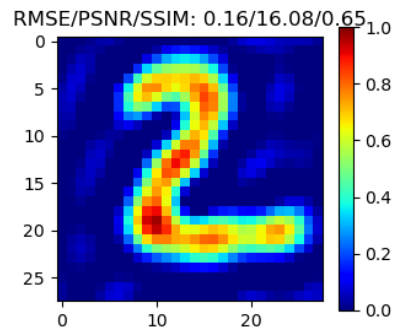
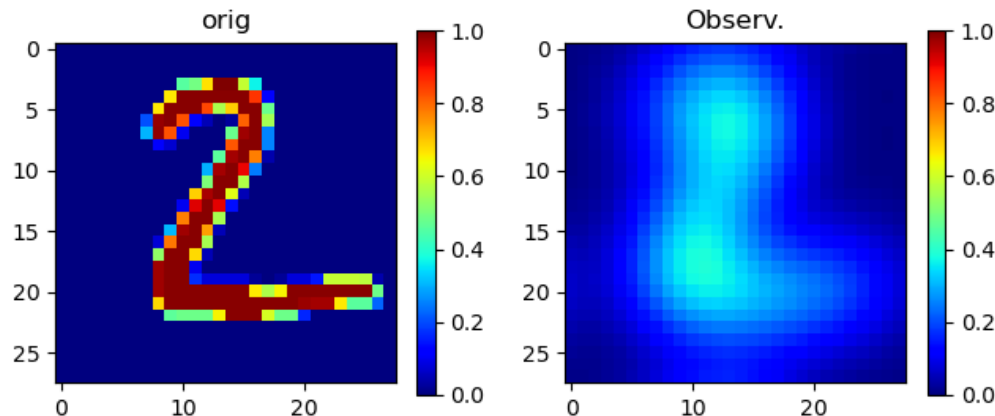
- Low-dimensional but highly non-linear
- Lemma: Bayes estimators are inconsistent

Inference in variable space

$$y|x \sim N(Ax, \sigma^2 I)$$

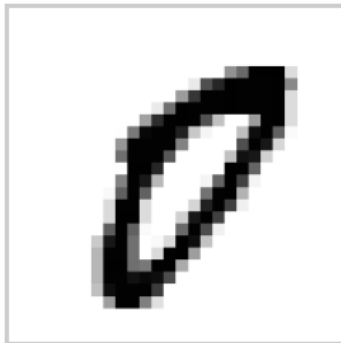
- High-dimensional but linear problem
- Lemma: Bayes estimators are consistent

Numerical results – comparison of inference methods

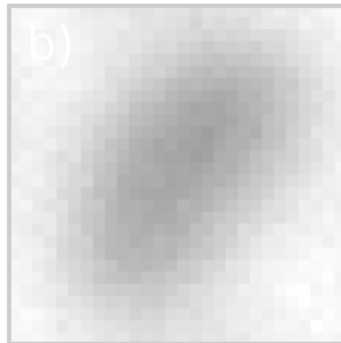


Numerical results – comparison of inference methods

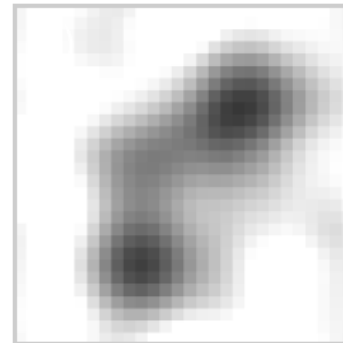
Ground truth



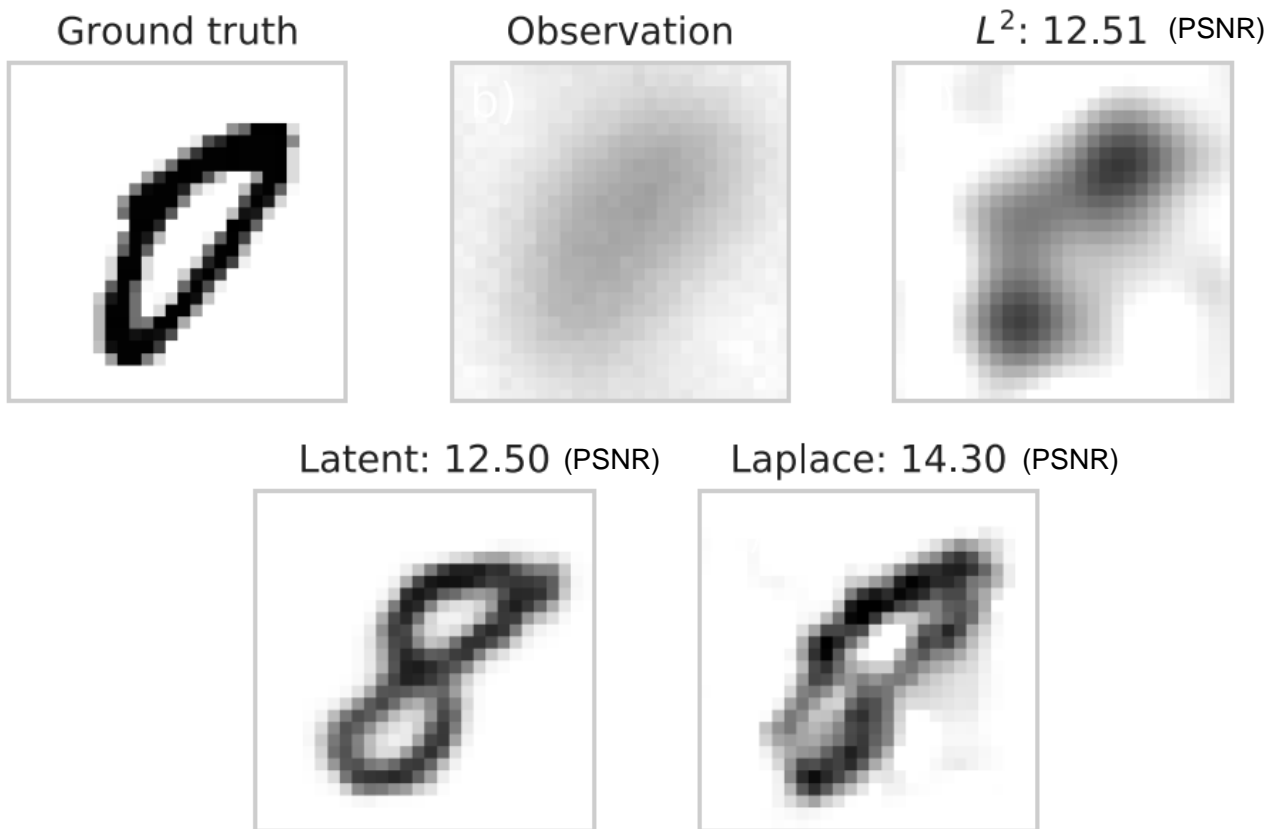
Observation



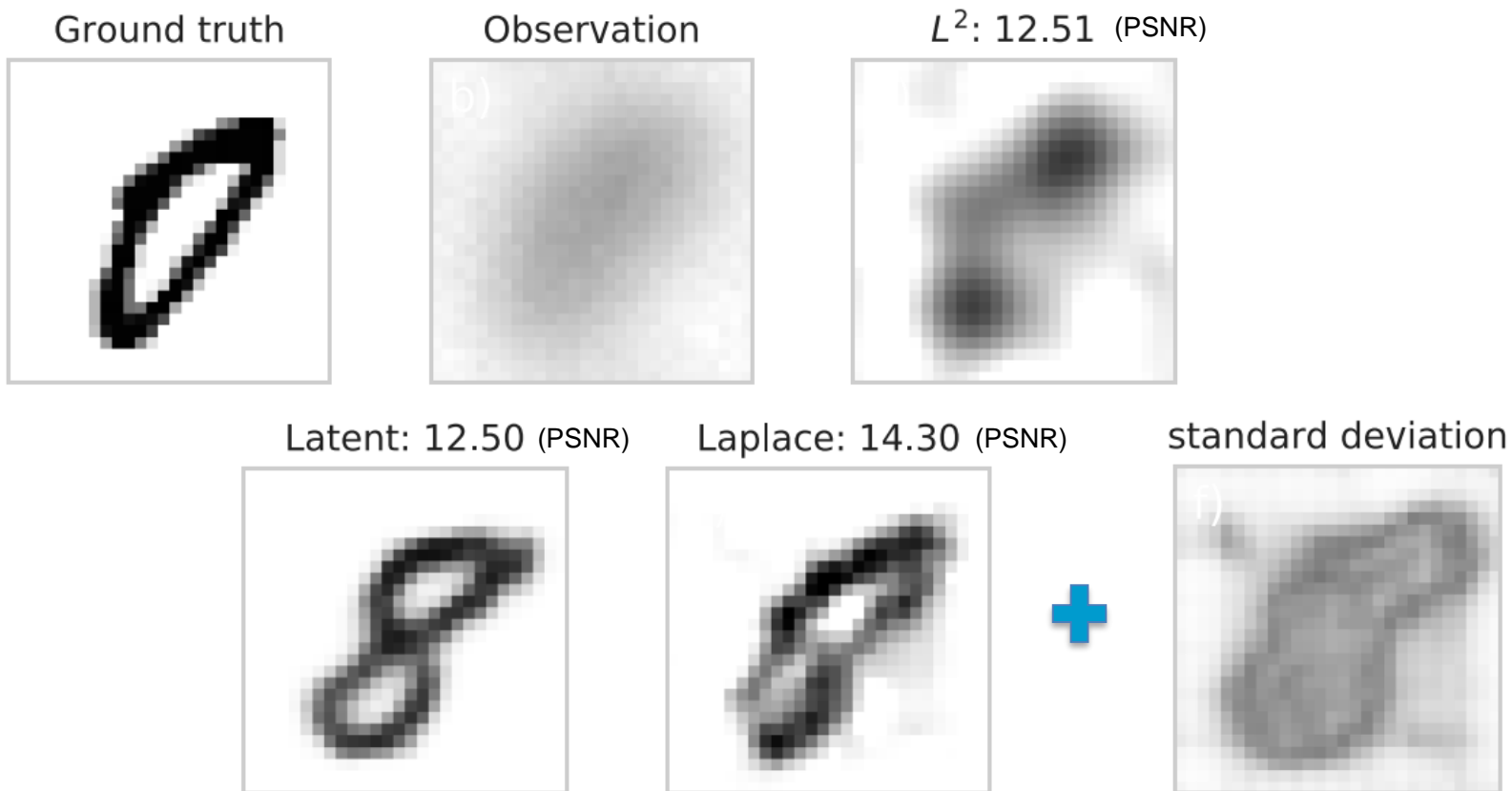
L^2 : 12.51 (PSNR)



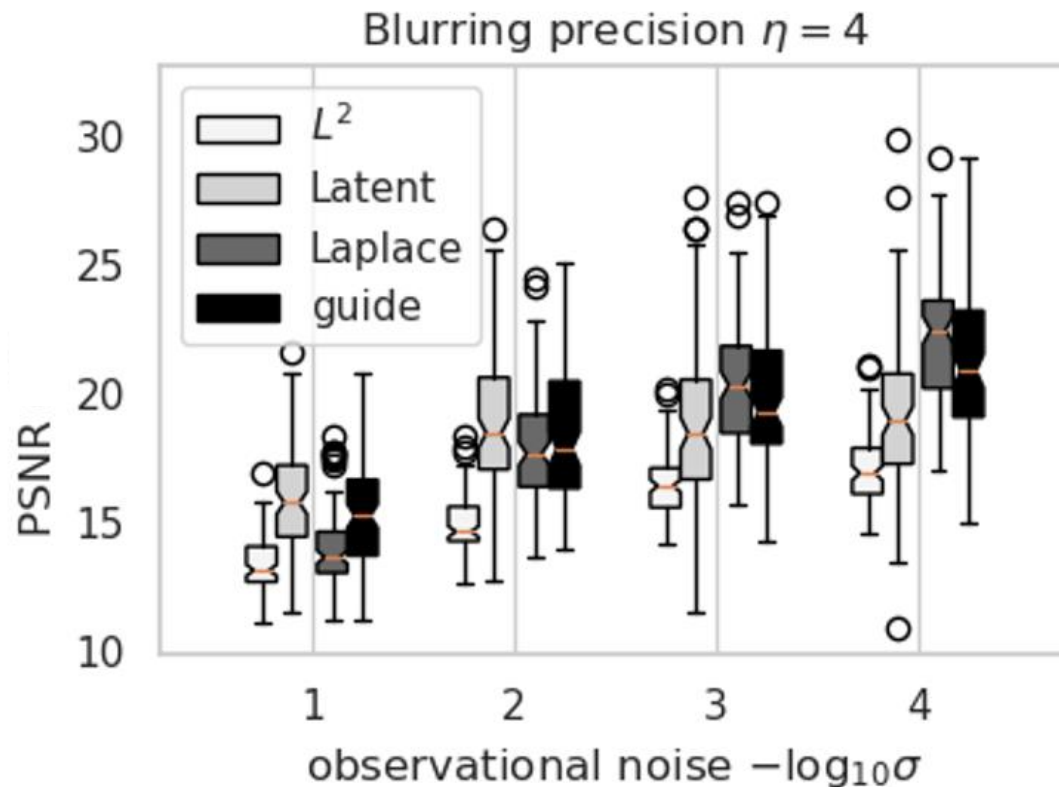
Numerical results – comparison of inference methods



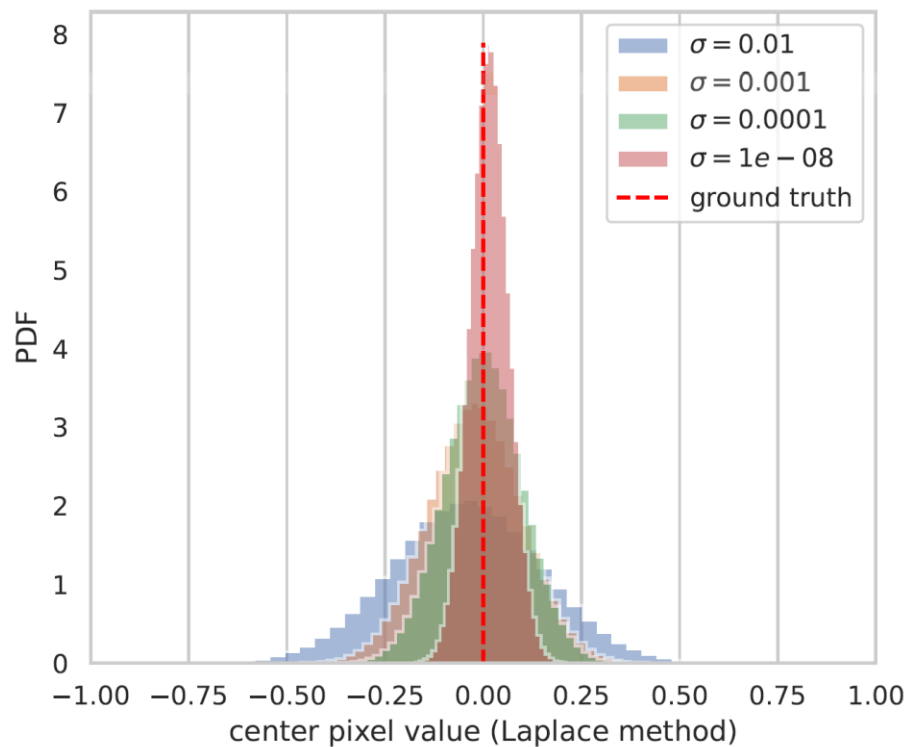
Numerical results – comparison of inference methods



Numerical results – consistency and guidance



Numerical results - consistency



Application: qualitative MRI

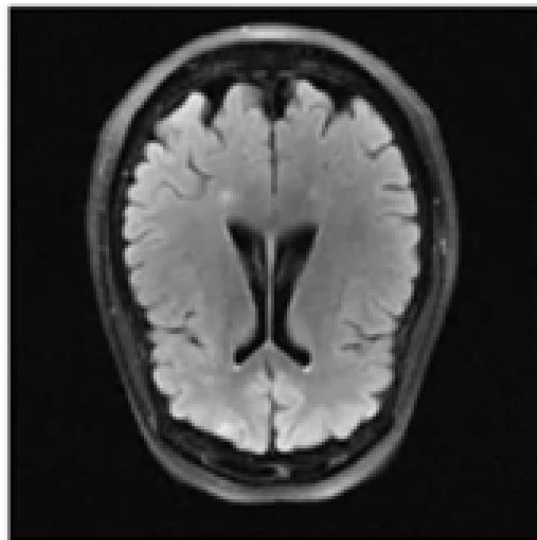
Observation in
Fourier domain

y



Reconstructed magnetization

x

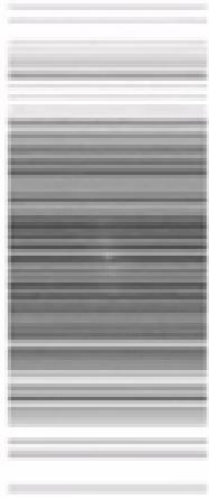


$$y|x, \sigma^2 \sim N(Ax, \sigma^2 I)$$

Application: qualitative MRI

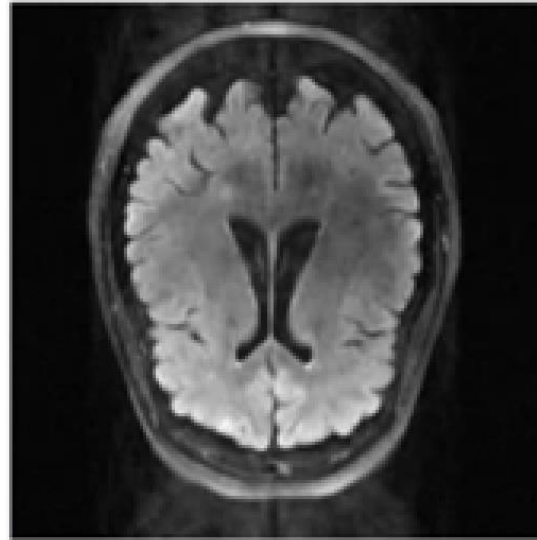
Observation in
Fourier domain

y



Reconstructed magnetization

x



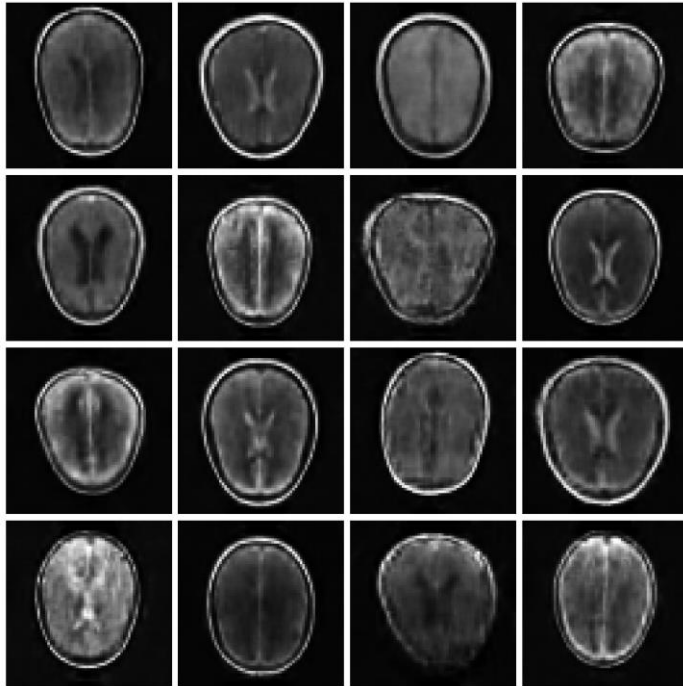
$$y|x, \sigma^2 \sim N(Ax, \sigma^2 I)$$

$$\pi(x) = ?$$

Aim: Reduction of measurement time (sparse observations in K-space)

Application: qualitative MRI

Generative model trained on clinical images: fastmri.org ~ 7000 brain MRIs



Randomly generated from VAE

- Generative models have a natural interpretation as prior in inverse problems
- Tools from machine learning can be applied
- Variable space prior models may lead to consistent Bayes estimators
- Latent space modelling may lead to inconsistent Bayes estimators



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Comparison

Latent space approach	Variable space approach
non-linear optimization required	computational infesible integral for every evaluation of prior
manifold restricted → inconsistency*	Not restricted → asymptotically consistent
low-dimensional (~10-100)	high-dimensional (~ $28^2 - 256^2$)
sampling from prior is easy and fast	sampling from prior is easy and fast

* If x not in image of g

Idea: linearize the generator map

$$g(z) = g(z_0) + J_{z_0}(z - z_0), \quad \Gamma(z) = \Gamma(z_0)$$

$$\pi(x) = \int_{\mathcal{Z}} \pi(x|z)\pi(z)dz \propto \int_{\mathcal{Z}} |\Gamma(z)|^{-1/2} \exp\left(-\frac{(x - g(z))^T \Gamma(z)^{-1} (x - g(z))}{2} - \frac{z^T z}{2}\right) dz$$

$$\pi(x) \approx \pi_L(x) = N\left(x|g(z_0) - J_{z_0}z_0, \Gamma(z_0) + J_{z_0}J_{z_0}^T\right)$$

Comparison again

Latent space approach	Variable space approach (Laplace)
non-linear optimization required	Analytic inversion possible
manifold restricted → inconsistency*	Not restricted → asymptotically consistent
low-dimensional (~10)	high-dimensional (~28 ²)
sampling from prior is easy and fast	Sampling from prior is difficult

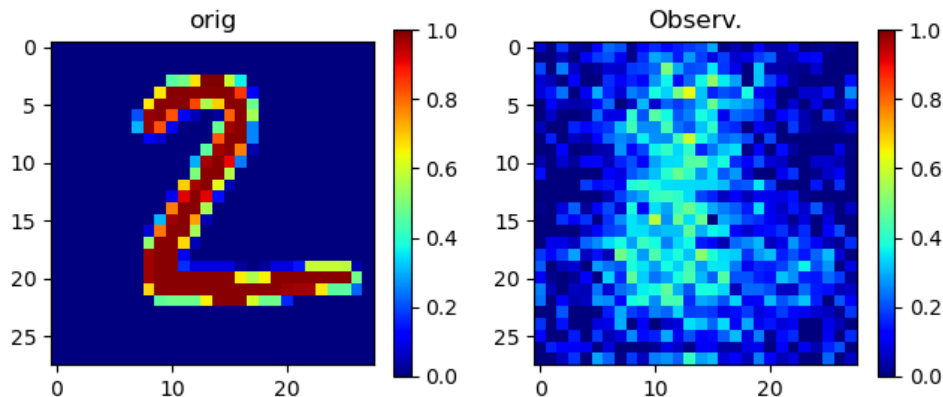
* If x not in image of g

Comparison again

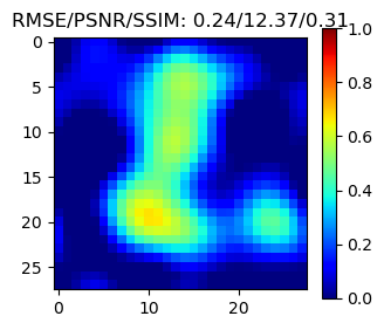
Latent space approach	Variable space approach (Laplace)
non-linear optimization required	Analytic inversion possible
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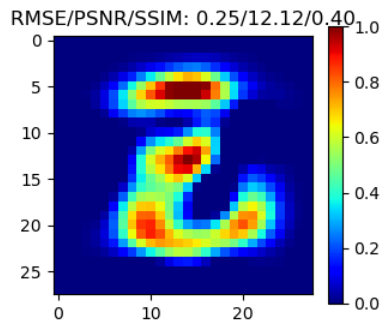
Numerical results



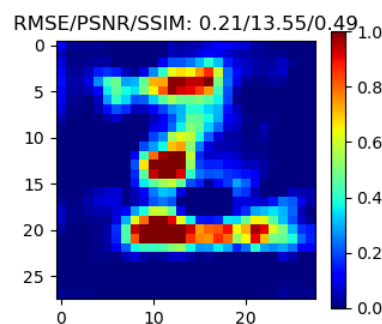
$$\sigma = 0.1$$



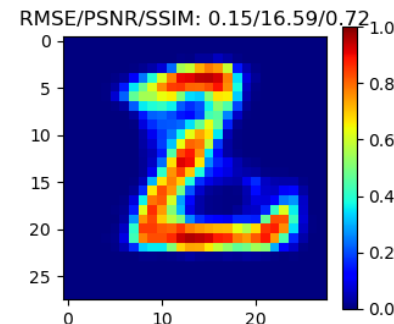
$N(0, \lambda^{-2})$



$N(\text{mean}, \text{cov})$



Laplace



Latent